

A Simple Model for the Generation of LRD Self-similar Traffic Using Piecewise Affine Chaotic One-dimensional Maps

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Abstract: A qualitative and quantitative extension of the chaotic models used to generate self-similar traffic with long range dependence LRD is presented by means of the formulation of a model that considers the use of piecewise affine one-dimensional maps. Based on the disaggregation of the temporal series generated, a valid explanation of the behavior of the values of Hurst's exponents is proposed and the feasibility of their control from the parameters of the proposed model is shown.

Keywords: Chaos, chaotic maps, Hurst exponent, self-similarity, traffic modeling in computer networks.

1. Introduction

The chaotic behavior of systems is an intermediate paradigm between two dogmatic scientific and philosophical concepts of the universe: absolute knowledge upheld by determinism, and total ignorance at the hands of randomness. Paradoxically, and supported by the existence of the above two dogmatic positions, an assertion as natural as the one made points at the main failure in the analysis of systemic behaviors: the extended use of dichotomies to characterize them.

It is in this scenario that the theory of chaos, defined by Kellert as the qualitative study of periodic and unstable behavior in deterministic and nonlinear dynamic systems [1], invades and establishes the omnipresence of unpredictability as a fundamental trait of common experience [2]. Then, the theory of chaos, instead of trying to understand the behavior of systems in a merely quantitative manner to determine exactly their future states, it concerns with understanding of a long-term behavior, searching for patterns under a holistic philosophy rather than a reductive philosophy.

As can be seen and inferred from the ideas given above, and in full agreement with the spirit of this research, it is neither possible nor practical to approach the problem of the characterization of the behavior of the systems of interest considering the full

conceptual extension of the theory of chaos, and for that reason it is accepted that chaos is the phenomenon by which low-order nonlinear systems show an apparently random complexity and behavior [3]. These systems are of low order because they can be described correctly by a reduced number of variables and parameters. They are also dynamic systems, i.e., with the variables of interest, which are deterministic, evolve over time, because the values of those variables at any instant of time can be determined only from their previous values given a set of dynamic laws. Finally, those dynamic laws that describe the system evolution in time are nonlinear (they do not fulfill the superposition principle) [4].

At this point it is convenient to make it clear that chaotic systems differ from conventional dynamic systems in the sense that they are intrinsically unpredictable, a fact that is evident even when its subjacent dynamic laws are of a deterministic character. But the above does not have to lead to the belief that chaos implies unpredictability, since that is only partially true because of the existence of two main sources of unpredictability, namely the inaccuracy of the initial data, and its origin as a characteristic inherent to certain nonlinear relations between numerical variables [5]. Therefore, the definition of chaos as a property of a system refers to its sensitivity to the initial conditions, i.e. that

given two trajectories arbitrarily close to one another in the phase space of a chaotic system, they diverge at an exponential rate given by Lyapunov's global exponent.

Note that it is certainly paradoxical for an essentially deterministic system, with deterministic dynamic laws, to show a chaotic behavior, since the basic premise of dynamic systems is that the knowledge of the initial conditions makes possible the determination of the system's future behavior at any time. In practice, the initial conditions can only be specified with finite precision. These uncertainties introduced in the initial conditions for the case of chaotic systems increase exponentially, and that explains the unpredictability of their behavior. Strictly, chaos involves the possibility of making good short-term predictions, but it makes impossible any long term prediction of a practical order [6]. A direct result of the above is that very simple systems, even with only one degree of freedom, such as those reported in [7] and [8], can give rise to surprisingly complex behaviors.

The notion of chaos often appears linked to the notion of fractal introduced by Mandelbrot [9], and even though it has not been proved rigorously, fractal properties seem inherent in chaotic processes, so apparently chaos and fractal sets are independent and unrelated concepts [4], [10]. However, keeping in mind that the fractal dimension concept raises a generalization of the notion of dimension through the introduction of the non-integer values for their specification, an extensively reported fact in its applications [11]; unexpectedly all chaotic systems tend to evolve asymptotically in their phase space toward a bounded region called strange attractor that has a non-integer dimension, i.e., a fractal. It can thus be argued that very often the strange attractors are fractals in their nature and are capable of exhibiting their complexity over different time or space scales. Because of the above it is therefore possible to state that the concepts of fractal geometry can be used to describe the evolutionary characteristics of chaotic systems, and chaotic systems in turn can be used conveniently as generators of fractal structures, thereby implying self-similarity and therefore its characterization index: Hurst's exponent (H).

It should be pointed out that since there is no simple definition of fractals, they are generally defined in terms of their attributes, such as, for example, the slow decay of their variances, the hyperbolic tail distribution of the time density between successive arrivals, the infinite order moments or poorly defined statistics, $1/f$ noise, long range dependence, self-similarity, and the previously mentioned non-integer dimension, among others [12]-[21]. The presence of such characteristics in the traffic flows of actual high speed computer networks is, therefore, the ultimate aim of the whole discussion presented.

Statistically, self-similar behavior of traffic flows in the present settings of high speed computer networks, is a fact that has been extensively reported for the different levels of telematics systems coverage [22]-[35], transmission technologies [36]-[46], control and signaling protocols [47], [48], and applications, particularly in video [49]-[54].

Similarly, the problem of the characterization of traffic has received considerable attention in the literature, giving rise to a number of proposals of stochastic models, among which we can name, without the list being exhaustive, Generalized Switched Poisson Processes (GSPP) [55], Markov Modulated Poisson Processes (MMPP) [56], Switched Poisson Processes (SPP) [57], Fractal Point Processes (FPP) [58], [59], Alternating Fractal Renewal Processes (AFRP) and their Extended Alternating Fractal Renewal Process (EAFRP) variant [23], [60], those based on intermittent chaotic maps [3], [4], [61]-[63], and the traditional processes of fractional Gaussian noise (fGn) and fractional Brownian motion (fBm) [64]-[67].

However, and in spite of all the efforts underlying the arguments and methodologies stated above, two problem situations inherent in the generation of traffic with long range dependence are ubiquitous, namely the degree of representatives of Hurst's exponent as a unique parameter for characterizing its effects on the performance of the tails systems in which it appears, and the behavior shown by its value in the self-similar second order series obtained within the interval of interest $0.5 < H < 1.0$. In this respect, [68]-[71] show in an isolated way both problems and their implications. Then, the set of both problem situations, and particularly that of

their final repercussions on the systems that are being studied, are called locality of Hurst's exponent.

Putting our attention on the existing set of models that use one-dimensional chaotic maps, this work presents an extension of them with the incorporation of piecewise affine maps to produce a self-similar traffic model with long range dependence that also provides an explanation for the locality of Hurst's exponent for the generated traffic and mitigates its effects.

In this paper, a qualitative and quantitative extension of the chaotic models used to generate self-similar traffic with long range dependence is presented by means of the formulation of a model considering the use of piecewise affine one-dimensional maps. Based on the disaggregation of the temporal series generated, a valid explanation of the behavior of the values of Hurst's exponents is proposed and the feasibility of their control from the parameters of the proposed model is shown.

2. Chaotic Maps and Self-similar Traffic

The use of chaotic maps as models of traffic was proposed for the first time in [3], [4], [48] starting from the pioneering work [72], and in essence a chaotic map is a variant of the on-off traffic model of [23], with the basic difference that its basis lies in the discrete dynamics instead of in the traditional probabilistic approaches.

A chaotic system characterized by a certain nonlinear function $f: D \rightarrow D$ with $D \subseteq \mathbb{R}^m$ is available. The system evolves according to the process' equation, defined by f , which for a discrete system is given by

$$\mathbf{x}[k] = f(\mathbf{x}[k-1], u[k-1]; \boldsymbol{\theta}) + \mathbf{v}[k] \quad (1)$$

where, $\mathbf{x}[k]$ is the system's state vector, $u[k]$ is the input excitation, $\mathbf{v}[k]$ is the noise vector of the process, and $\boldsymbol{\theta}$ is the vector of the system's parameters.

In general, the state of the system cannot be observed directly, so samples of it (or of functions of it) are required that are obtained by means of a measuring process given by

$$\mathbf{y}[k] = g(\mathbf{x}[k]) + \mathbf{w}[k], \quad \text{with } k = 0, \dots, N \quad (2)$$

where g is the measurement function (which can be known or not), $\mathbf{y}[k]$ is the

measurements vector, and $\mathbf{w}[k]$ is the noise vector of the measurement.

A chaotic map is an application $f: X \rightarrow Y$ that associates each element $x \in X \subseteq \mathbb{R}^m$ with a single element $y \in Y \subseteq \mathbb{R}^q$, where X is the domain of f and Y is the arrival set of f .

Let $f: D \rightarrow D$ be an application with $D \subseteq \mathbb{R}^m$. An iterated map is the system formed by the set of m equations given by

$$\mathbf{x}[n] = f(\mathbf{x}[n-1]; \boldsymbol{\theta}) \quad (3)$$

As seen from (3), a chaotic map is a class of discrete autonomous system, and this work deals exclusively with one-dimensional maps, a fact for which it is convenient to establish that a one-dimensional chaotic map is an application $f: D \rightarrow D$ with $D \subseteq \mathbb{R}$ such that

$$x[n] = f(x[n-1]; \theta) \quad (4)$$

The definition of chaos as a property of a chaotic system refers to its sensitivity to the initial conditions. Then, considering a chaotic map defined by $x_{n+1} = f(x_n)$ and two trajectories with almost identical initial conditions x_0 and $x_{0+\varepsilon}$, where $\varepsilon \rightarrow 0$, its sensitivity to the initial conditions is described by the expression

$$|f^N(x_0 + \varepsilon) - f^N(x_0)| = \varepsilon \exp[N\lambda(x_0)] \quad (5)$$

where $f^N(\cdot)$ represents the N^{th} iteration of the map, and $\lambda(x_0)$ is Lyapunov's global exponent which describes the exponential divergence. For the map to be chaotic this parameter must be positive for most of the x_0 [73]. Then (5) implies which points that begin with similar initial conditions develop along different trajectories.

Let $f: I \rightarrow I$ be an application. It is said that $f(x)$ is a one-dimensional piecewise affine map (PWA) if there is a finite number of points $e_0 < e_1 < \dots < e_M$, such that the interval $I = [e_0, e_M]$ can be subdivided into M smaller intervals $E_i = [e_{i-1}, e_i]$, with $i = 1, \dots, M-1$ and $E_M = [e_{M-1}, e_M]$, within which $f(x)$ is affine. Mathematically, a PWA map is expressed as

$$f(x) = \sum_{i=1}^M (a_i x + b) \Psi_{E_i}(x) \quad (6)$$

where Ψ denotes the characteristic or indicator function defined as follows.

Let $\Psi_R: D \rightarrow \{0,1\}$ be an application with $D \subseteq \mathbb{R}$. It is said that Ψ_R is the characteristic or indicator function of region R if it has the form

$$\Psi_R = \begin{cases} 1, & x \in R \\ 0, & x \notin R \end{cases} \quad (7)$$

In other words, $f(x)$ has a similar behavior within each of the M intervals E_i into which the arrival interval I is divided as if it were observed in the whole interval I . From some point of view, this fact puts in evidence the self-similarity.

A one-dimensional map composed of two intervals, in which the state variable x_n evolves in time according to two functions $f_1(\cdot)$ and $f_2(\cdot)$ that satisfy condition (5), allows writing it, from the development of (4), as

$$x_{n+1} = \begin{cases} f_1(x_n), & 0 < x_n \leq d \\ f_2(x_n), & d < x_n < 1 \end{cases} \quad (8)$$

This notation makes it possible to conceive a mesh generation process considering that the source of origin is in a passive state or in an active state (in a similar way as the case of the on-off models) at a given moment n , as a function of whether the value of the state variable x_n is above or below a certain activation threshold d . In this way all the iterations of the map in the active state correspond to mesh (or a gust of meshes) generation processes, and all the iterations of the map in the passive state to time processes between successive arrivals.

Under the same reasoning logic, and considering the permanence of the map in one or the other previous states, the evolution of the mesh arrival process is described from the indicator function (7), which, for the sake of consistency with the notation used in (8), can be written as

$$y_n = y(x_n) = \begin{cases} 0, & 0 < x_n \leq d \\ 1, & d < x_n < 1 \end{cases} \quad (9)$$

An interesting interpretation of the above model is reported in [74], considering it formed by two dynamic layers, one hidden given by x_n and one visible specified by y_n .

It is particularly interesting to see that the behavior of a trajectory over which the map given by (8) evolves is such that it does not have to visit the two regions of its phase space with equal frequency, and furthermore, there is no reason to consider, even within the same attractor, a uniform probability density function of the generated sequences, so it is reasonable to ask about the frequency with which a given trajectory visits each region of

the map in an observation interval of n iterations, as well as about the way of calculating such probability density function from an initial condition x_0 .

In this respect, the reply to both questions is found in the density distribution of the map's states, $\rho_n(x)$, [75]

$$\rho_n(x) = \frac{1}{N} \sum_{i=1}^N \delta[x - x_n(i)] \quad (10)$$

where $\delta(x)$ is Dirac's delta function and the evolution of $\rho_n(x)$ is in agreement with the equation of Frobenius-Perron [76]

$$\rho_{n+1}(x) = \int \delta[x - f(z)]\rho_n(z)dz \quad (11)$$

In the case of a one-dimensional map given by $x_{n+1} = f(x_n)$, with $x_n \in [0,1]$, $n = 0, 1, 2, \dots$, from (10) we have that

$$\rho(x) = \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{n=0}^N \delta[x - f_n(x_0)] \quad (12)$$

If $\rho(x)$ does not depend on x_0 , the system is ergodic [75], and therefore it is true that

$$\begin{aligned} \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{i=0}^N g(x_i) &\equiv \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{i=0}^N g[f^i(x_0)] \\ &= \int_0^1 \rho(x)g(x)dx \end{aligned} \quad (13)$$

However, since $\rho_n(x)$ must be stationary because of (13), i.e., it does not have to depend on instant n , it is known as the invariant density of map $f(x)$ [48], and it describes the iteration density of x_n in the interval $(0,1)$ when $n \rightarrow \infty$. Therefore, $\rho_n(x)$ is a self-function of the Frobenius-Perron operator with self-value 1, and therefore

$$\rho(x) = \int_0^1 \delta[x - f(z)]\rho(z)dz \quad (14)$$

A concise presentation of the set of facts, that give rise to the treatment of traffic considering its self-similar nature and LRD, converge in the need to capture its fluctuations on different time scales in order to make assertive forecasts of the yield of communications systems. In this respect, self-similarity contributes the parsimony required to specify the statistical details of the variables involved from a minimum set of modeling parameters, and a model based on the theory of complexity contributes the robustness needed to cohere those parameters with information.

3. Specification of the Chaotic Model

For simplicity, the deduction of the model is approached as follows.

Consider the nonlinear double intermittence map proposed in [4]

$$x_{n+1} = \begin{cases} \varepsilon_1 + x_n + c_1 x_n^{m_1}, & 0 < x_n \leq d \\ -\varepsilon_2 + x_n - c_2 (1 - x_n)^{m_2}, & d < x_n < 1 \end{cases} \quad (15)$$

where

$$c_1 = (1 - \varepsilon_1 - d) / d^{m_1} \quad (16)$$

and

$$c_2 = (d - \varepsilon_2) / (1 - d)^{m_2} \quad (17)$$

and the indicator function is given by (9)

If $m_2 = 1$ and $\varepsilon_2 = 0$, from (15) we get the model of a nonlinear chaotic intermittent map [3]

$$x_{n+1} = \begin{cases} \varepsilon + x_n + c x_n^m, & 0 < x_n \leq d \\ (x_n - d) / (1 - d), & d < x_n < 1 \end{cases} \quad (18)$$

where

$$c = (1 - \varepsilon - d) / d^m, \text{ with } \varepsilon \ll d \quad (19)$$

The map's parameters (ε , m , d) are used to control the probability of permanence in the inactive state, the traffic load; i.e., the mean rate of mesh arrival, and the degree of self-similarity density, H . Specifically, the fit of ε incides on the probability of permanence of the iterations of the map in the inactive state, while the traffic load depends on parameters m and d [77], [78].

The condition $\varepsilon \ll d$ is well defined, at least theoretically, if $\varepsilon = 0$, which leads to the control of the limit of the range of temporal scales over which LRD is observed. In [77] it is shown that if $\varepsilon = 0$, permanence time can be of any length, but as ε increases above 0, the escape time from the region tends to a fixed upper limit.

Considering $m = 1$ with the purpose of decreasing the degree of the function that characterizes the inactive state of the map implies generating traffic with short range dependence (SRD), which is verified from the relation existing between H and m given by $H = (3m - 4) / (2m - 2)$, with $m = \max\{m_1, m_2\}$ [79], i.e., $H = 0.5$. In other words, a geometric type decay takes place for the

map's regions, which is synonymous with uncorrelated traffic, i.e., traffic with short range dependence.

Therefore, the proposed map model together with its indicator function is given by

$$x_{n+1} = \begin{cases} x_n + x_n^m, & 0 < x_n \leq d \\ (x_n - d) / d^m, & d < x_n < 1 \end{cases} \quad (20)$$

and

$$y_n = y(x_n) = \begin{cases} 0, & 0 < x_n \leq d \\ 1, & d < x_n < 1 \end{cases} \quad (21)$$

Rewriting (20) in the form

$$x_{n+1} = \begin{cases} f_1(x) = x_n + x_n^m, & 0 < x_n \leq d \\ f_2(x) = (x_n - d) / d^m, & d < x_n < 1 \end{cases} \quad (22)$$

from the development of (14) and applying (22) we get

$$\rho(x) = \int_0^d \delta[x - f_1(z)] \rho(z) dz + \int_d^1 \delta[x - f_2(z)] \rho(z) dz \quad (23)$$

an equation for which Schuster [73] establishes the existence of only one physically relevant solution that is obtained from $z = 1/f_i(x)$, i.e.,

$$\rho(x) = \frac{\rho[f_1^{-1}(x)]}{f_1'[f_1^{-1}(x)]} + \frac{\rho[f_2^{-1}(x)]}{f_2'[f_2^{-1}(x)]} \quad (24)$$

where f_i' represents the first derivative of f_i . Then the expression for the invariant density is given by

$$\rho(x) = \sum_{i=1}^2 \frac{\rho(y_i)}{f_i'(y_i)}, \text{ with } y_i = f_i^{-1}(x) \quad (25)$$

which allows obtaining the system's load, i.e., the probability of remaining in the active state, from the integration of (25) between the limits d and 1.

4. Experimental Results

The self-similar behavior with LRD of the traffic generated by the proposed model is confirmed by means of the calculation of Hurst's exponent using the rescaled range analysis (R/S) [63], [80] and the aggregate variance analysis (Var) [81], [82]. In the R/S analysis the value of H is obtained directly

from the slope of the double logarithmic plot, while in the aggregate variance analysis H is obtained from the relation $H = 1 - \beta / 2$ where $0 < \beta < 1$ [83], [84].

In this first stage of the research no online traffic is generated because we are dealing only with the validation of the model; and instead of it all the necessary algorithms are programmed in MATLAB language.

As a first point, two values are specified in Table I for parameter m , keeping the number of the map's iterations N and parameter d fixed.

Tables II to IV show different experiments varying parameters m and d for a constant number of iterations of the model, to obtain the Hurst parameter H .

Figures 1 and 2 show the behavior of x_{n+1} and y_n for the data of Table 1. Figure 1(b) shows the first 125 iterations for y_n as the rest, to iteration $N = 1000$, are zero.

Figure 3 shows the graphic aspect of the traffic generated for $N = 1000$ iterations, $d = 0.5$ and $m = 2$ (this case corresponds to Figure 2).

Table 1. Specification of the model's parameters

| N | d | m | Show in |
|------|-----|-----|----------|
| 1000 | 0.5 | 1 | Figure 1 |
| | | 2 | Figure 2 |

Table 2. Specification of the model's parameters

| N | d | m | H | |
|------|-----|-----|------|------|
| | | | R/S | Var |
| 1000 | 0.5 | 1 | 0.50 | 0.42 |
| | | 1.2 | 0.51 | 0.46 |
| | | 1.4 | 0.54 | 0.50 |
| | | 1.6 | 0.68 | 0.58 |
| | | 1.8 | 0.73 | 0.68 |
| | | 2 | 0.87 | 0.78 |

Table 3. Specification of the model's parameters

| N | d | m | H | |
|------|-----|-----|------|------|
| | | | R/S | Var |
| 1000 | 0.3 | 1 | 0.50 | 0.44 |
| | | 1.2 | 0.51 | 0.47 |
| | | 1.4 | 0.61 | 0.56 |
| | | 1.6 | 0.72 | 0.65 |
| | | 1.8 | 0.78 | 0.72 |
| | | 2 | 0.90 | 0.82 |

Table 4. Specification of the model's parameters

| N | d | m | H | |
|------|-----|-----|------|------|
| | | | R/S | Var |
| 1000 | 0.1 | 1 | 0.51 | 0.44 |
| | | 1.2 | 0.53 | 0.50 |
| | | 1.4 | 0.66 | 0.56 |
| | | 1.6 | 0.75 | 0.65 |
| | | 1.8 | 0.81 | 0.72 |
| | | 2 | 0.92 | 0.82 |

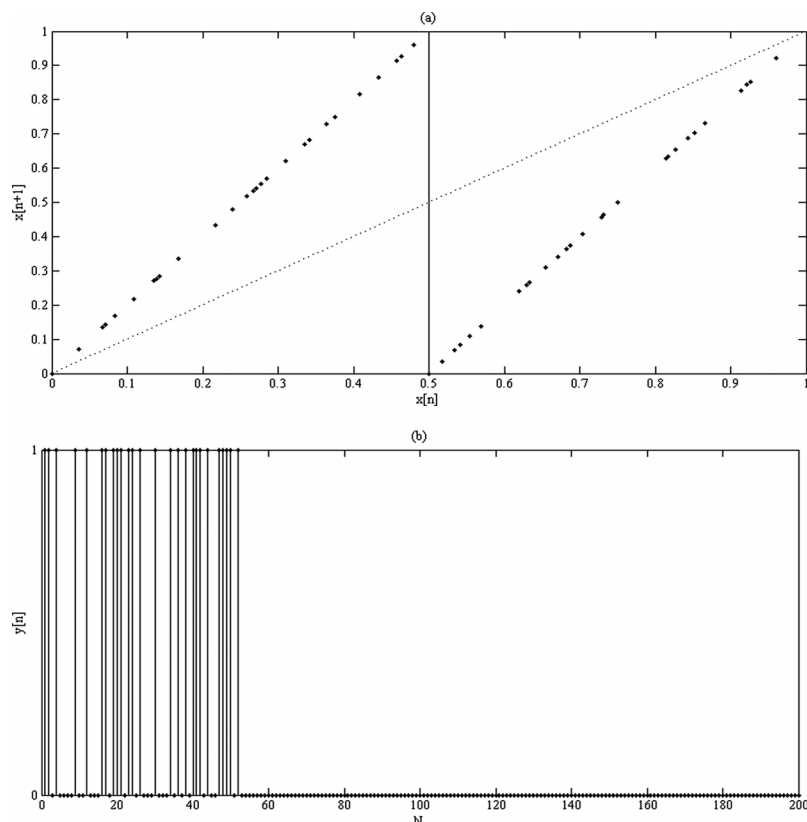


Figure 1. Behavior of the model considering $N = 1000$ iterations, $d = 0.5$ and $m = 1$.

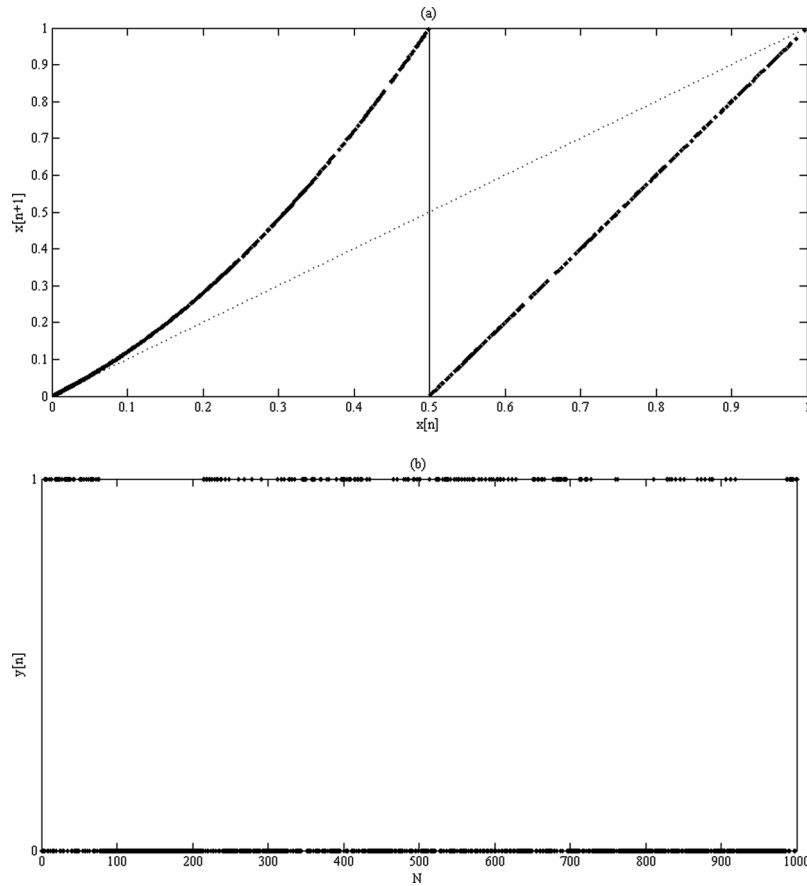


Figure 2. Behavior of the model considering $N = 1000$ iterations, $d = 0.5$ and $m = 2$.

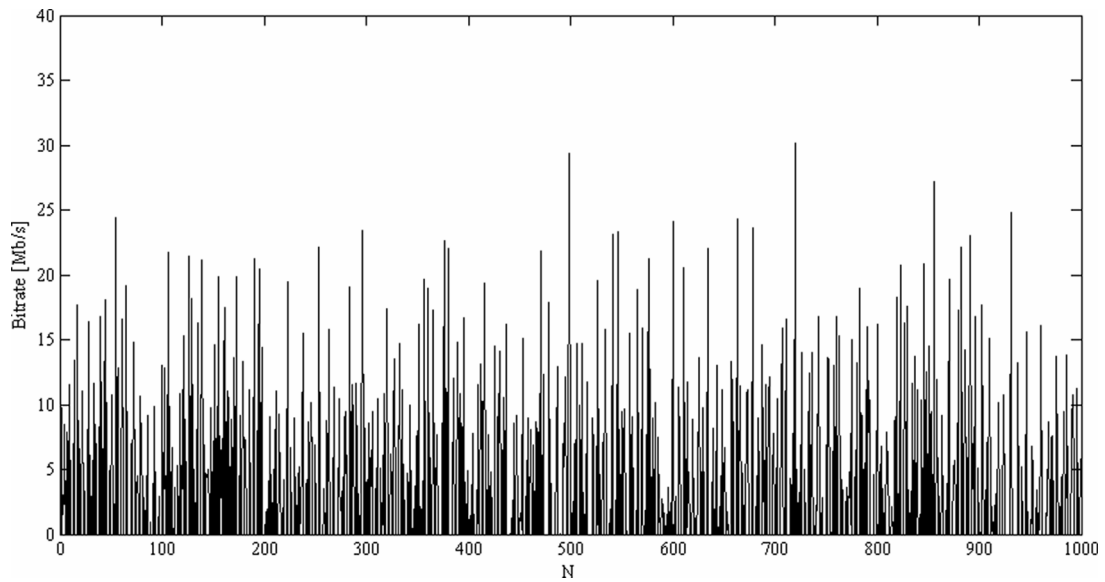


Figure 3. Traffic generated by the parameters map, $d = 0.5$ and $m = 2$, considering $N = 1000$ iterations.

Tables 5 to 7 present values of H for random traffic sequences extracted from the original series used to formulate Tables 1 to 3. These random sequences are formed from the extraction of the number of samples specified

under Random N , and they are then analyzed as samples of traffic generated directly by the model.

Table 5. H for disaggregated series

| N | Rand. N | d | m | H | |
|------|--------------|-----|-----|------|------|
| | | | | R/S | Var |
| 1000 | 500 | 0.5 | 1 | 0.42 | 0.37 |
| | | | 1.2 | 0.45 | 0.43 |
| | | | 1.4 | 0.51 | 0.48 |
| | | | 1.6 | 0.55 | 0.52 |
| | | | 1.8 | 0.65 | 0.58 |
| | | | 2 | 0.72 | 0.66 |

Table 6. H for disaggregated series

| N | Rand. N | d | m | H | |
|------|--------------|-----|-----|------|------|
| | | | | R/S | Var |
| 1000 | 500 | 0.3 | 1 | 0.44 | 0.38 |
| | | | 1.2 | 0.47 | 0.45 |
| | | | 1.4 | 0.53 | 0.51 |
| | | | 1.6 | 0.62 | 0.57 |
| | | | 1.8 | 0.67 | 0.62 |
| | | | 2 | 0.75 | 0.67 |

Table 7. H for disaggregated series

| N | Rand. N | d | m | H | |
|------|--------------|-----|-----|------|------|
| | | | | R/S | Var |
| 1000 | 500 | 0.1 | 1 | 0.43 | 0.38 |
| | | | 1.2 | 0.45 | 0.42 |
| | | | 1.4 | 0.52 | 0.50 |
| | | | 1.6 | 0.57 | 0.52 |
| | | | 1.8 | 0.63 | 0.57 |
| | | | 2 | 0.71 | 0.66 |

5. Discussion

The model shows that the generation of self-similar traffic with LRD can be approached from the control of parameters m and d considering a fixed number of iterations, as shown from the results given in Tables II-IV. However, because of its simplified present formulation, control of the permanence times in each state is not possible. In that respect, a general model like that of [48] does allow that with good accuracy. A simple example to illustrate that need is built on the basis of requiring that the traffic of a system should have a certain H , for example 0.90. Examining Table III and Table IV it is found that this requirement can only be satisfied by means of a change in the boundary of the iteration regions, which is impractical because of its repercussions on the indicator function. It is a need that requires urgent attention.

Control of the degree of self-similarity of the generated traffic seems to be effective for the subjacent temporal series. The analysis of the

results shown in Tables V-VII is fundamental because it reflects the underlying problem: controlling the effect of locality on Hurst's exponent. It is seen that the traces formed from random sections of the original samples reflect the behavior of the whole, and also that Hurst's exponent can be considered by itself as a valid indicator to characterize the effects of the generated self-similar traffic with LRD on the performance of the tail systems in which it appears. The lack of a formal mathematical proof of this fact is acknowledged, but in a first instance, based on the effect that the indicator function has on the perception of the system, an appropriate substantiation is found.

6. Conclusions

A qualitative and quantitative extension of the models for the generation of self-similar traffic with long range dependence has been presented here with the incorporation of piecewise affine maps, and a map model has been proposed that provides an interpretation of the locality of Hurst's exponent from the generated traffic.

The feasibility of having an efficient and effective self-similar traffic generator from the parsimony of its model is shown, a fact made evident by an adequate control of the value of Hurst's exponent.

Hurst's exponent is shown to be completely valid as a unique representative parameter to characterize self-similar traffic.

It is shown that the value of Hurst's exponent in the disaggregation of self-similar temporal series depends on the original model of the traffic. In this respect, based on subsets of samples obtained randomly, it is seen that its value shows a tendency to remain constant and in that way adequately characterize the segments in question.

Finally, the most relevant fact for the future development of this research is the practical proof that $m = 1$ must be definitively discarded as an option for the formulation of a chaotic model representative of self-similar traffic because it inevitably leads to SRD traffic, as shown by the results given in Tables I-VII, so it is shown to be impossible to work only with a linear model, making it also impossible for the model to be purely piecewise affine.

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